

Bosch Receiver Integration Guide

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Revision A0

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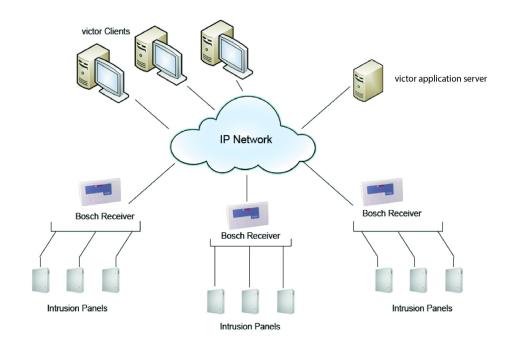
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Introduction

Bosch Overview

Bosch Integration provides advanced, seamless integration between victor and Bosch Receivers allowing users of **victor unified client** to monitor their Bosch devices from within the victor interface.





Features

The objective of the Bosch integration is to provide a standard, single interface between Bosch and American Dynamic's victor Unified Video Management product. Supported features include:

- Viewing status and information of configured Bosch Receivers
- Support for multiple Bosch Receivers
- · Adding new Bosch Receivers
- · Importing Alarm Points
- Support for Security Industry Association (SIA) and Contact Identification (CID) protocols
- All intrusion panels supported by Bosch receivers are supported in integration
- UDP communication
- · Integration with victor roles
- · Integration with victor Object Association
- Integration with victor journal allowing security and intrusion events to be reviewed together
- Client side event management
- Create / Edit / Delete Alarm point object for Zone and Partition
- •Alarm Categories The Alarm Categories Editor allows you to add categories like partitions, zones, panels etc.
- •Alarm Configuration The Alarm Configurations Editor allows configuration of existing alarms and new alarms.
- •Message Delivery tab in Receiver Editor The Message Delivery tab allows selection of message delivery and message filtering options.
- •Alarm Point Editor allows selection of multiple alarms for a single alarm point. A new category drop-down selection allows Alarm category selection.

Installation

Hardware and Software Requirements

Hardware

Bosch Receiver integration has the same hardware, software, and disk space requirements as the unified Application server and victor site manager. Therefore, if the machine can successfully run victor then it will satisfy Bosch Receiver integration requirements.

Bosch Receiver integration requires approximately 50MB of available Hard Disk space.

Software

Refer to latest release notes for current software version

Bosch Receiver Firmware

- Bosch Connectix D6100 Receiver with firmware version 61.04.00
- Bosch Connectix D6600 Communications Receiver with firmware version 01.03.03

Operating Systems

All operating systems supported by victor are supported by this driver. Refer to victor product data sheets

Installation

The Bosch Receiver installer must be run on both victor site manager and all victor unified client machines.

Procedure 2-1 Adding Bosch Receiver Integration to victor

Step	Action
1	Close any currently running programs.
2	Navigate to http://www.americandynamics.net.
3	Download the appropriate version of the Bosch Integration Software Driver for your version of victor.
4	Launch the Bosch Integration Software Driver.
5	Read the End User Licence Agreement (EULA) and click I accept the terms in the license agreement, then click Next.



- For server installations running the Crossfire service, the **Tyco Crossfire Service Alert** dialog box appears. Click **OK** to continue with installation.
- 7 Click Next in the Bosch Integration Setup Wizard to install the integration.
- 8 Click **Install**. The program may take several minutes to install.

Note

If you choose to enable the driver for redundancy, select the **Redundant Server installation using supported third party redundancy** check-box and enter the Virtual server (alias) name.

9 Click **Finish** to complete the installation.

After installation, a new group called **Intrusion** is available on the **Setup** tab.

- End -

Procedure 2-1-1 Modifying the Virtual Server (alias) name during or after installation

Navigate to the folder ../Tyco/CrossFire/ServerComponents Open the Bosch Reciever Driver Service.exe file. Scroll down to the client section and change the local host to the required Virtual server (alias) name. Do this for all end points except TraceViewerURI.

Configuration

Hardware Requirements

- Bosch Connectix D6100 Receiver with firmware version 61.04.00
- Bosch Connectix D6600 Communications Receiver with firmware version 01.03.03
- Bosch D6882 Ethernet Network Adapter

Configuring the Bosch Receiver to Communicate with victor Unified Client

The Bosch D6882 Ethernet Network Adapter must be configured prior to the Bosch Connectix 6600 Receiver and Bosch Connectix 6100 Receiver in order for communication with the victor Unified Client.

Bosch D6882 Ethernet Network Adapter

Enter the following settings to configure the Bosch D6882 Ethernet Adapter:

Parameter	Setting
Baud Rate	38400
I/F Mode	4C
Flow	00
Port	The Alarm Port must be between 1025 and 65535
Connect Mode	CC
Datagram Type	02

Bosch Connectix D6600 Receiver Configuration

Enter the following settings to configure the Bosch Connectix D6600:

Parameter	Section	Settings	Comments
Output Format	2.5.15	2	
RS232 Direct Access Permission	4.5.9	0	



COM4NetworkAdapter	6.1.5	2	 When connecting to a network adapter, this value must be set to 1 When connecting the PC running the D6200 to RS232, this value must be set to 0
			If the D6600 is connected with D6682 then the value must be set to 2
COM4 Network Encryption Enable	6.1.6	0	
Network Automation Connection	6.3.1	(xxx).(xxx).(xxx). (xxx)	Provide the IP address of the PC where the Bosch integration is installed
Port	6.3.2	(xxxx)	The Bosch Receiver port number must match the port number configured in victor Unified Client
			Default: 10000
Polling Inteval	6.3.3	30	
Retry Number	6.3.4	4	
ACK Wait	6.3.5	4	
Network Automation Output Format	6.3.6	2	
Device	6.3.7	1	

Bosch Connectix D6100 Receiver Configuration

Enter the following settings to configure the Bosch Connectix D6100:

Parameter	Section	Settings	Comments
Output Format	2.5.15	2	
RS232 Direct Access Permission	4.5.9	0	
COM4NetworkAdapter	6.1.5	2	This parameter is not present in the Bosch D6100 Receiver.
			This parameter can be configured from the D6200 programming software.
COM4 Network Encryption Enable	6.1.6	0	This parameter is not present in the Bosch D6100 Receiver.
			This parameter can be configured from the D6200 programming software.
Network Automation Connection	6.3.1	(xxx).(xxx).(xxx). (xxx)	Provide the IP address of the PC where the Bosch integration is installed
Port	6.3.2	(xxxx)	The Bosch Receiver port number must match the port number configured in victor Unified Client
			Default: 10000
Polling Inteval	6.3.3	30	
Retry Number	6.3.4	4	
ACK Wait	6.3.5	4	
Network Automation Output Format	6.3.6	2	
Device	6.3.7	1	

- End -

Configuring Sync Time in the Bosch Connectix Receiver

Procedure 3-1 Configuring Sync Time in Bosch Connectix Receiver D6100

Step	Action
1	On the D6100 keypad, press Menu and enter the default passcode 6100 to enter the programming mode. Press Enter
2	Scroll down to 2 CPU Configuration and press Enter.



- 3 Scroll down to 2.2 Global and press Enter.
- 4 Scroll down to **2.2.4Enable Input Commands** and press **Enter**.
- 5 Set **Enable Input Commands** to a value of 1. Press **Enter** > 1 > **Enter** to set this value. This value enables time sync for the receiver with the Host.

Procedure 3-2 Configuring Sync Time in Bosch Connectix Receiver D6600

Step	Action
1	On the D6100 keypad, press M/E and enter the default passcode 6600 to enter the programming mode. Press M/E .
2	Scroll down to 2.2 Global and press M/E.
3	Scroll down to 2.2.4 Enable Input Commands and press Enter.
4	Set Enable Input Commands to a value of 1. Press M/E > 1 > M/E to set this value. This value enables time sync for the receiver with the Host.
	- End -

Administration

Introduction

Detailed Hardware Information

Detailed hardware information is available for all configured Bosch Receivers. To access this information, select **Bosch Receivers** from the **Setup** tab, then select **Show All**. Right-click the receiver you wish to view information for and select **Edit**. This information is also available by right-clicking on a receiver in the Device List and selecting **Edit**.

Roles

Bosch Receivers privileges are associated with victor roles, therefore all context menu verbs associated with Bosch Receivers are added to existing victor roles which can be edited accordingly. For more information on Roles, refer to the *victor unified client Configuration and User Guide*.

Associations

Bosch Receivers support victor's Object Association. Object Association refers to linking unrelated victor objects with the intent of enabling incident building capability. For more information on Object Associations, refer to the *victor unified client Configuration and User Guide*.

Reports

Bosch objects are included in the report selection tool and support the victor **Find in Journal** feature. For more information on Reports and the Find in Journal feature, refer to the *victor unified client Configuration and User Guide*.

Events

Bosch Receivers support victor Events, allowing you to detect, monitor and record specific activities on the system. For further information on Events, refer to the *victor unified client Configuration and User Guide*.

Maps

Bosch objects support victor Maps and the **Find on Map** feature. For more information on Maps and the Find on Map feature, refer to the *victor unified client Configuration and User Guide*.



Administration Functions

The Bosch Receiver editor in victor unified client allows configuration of alarm and alarm categories, modifying connection and communication details and alerts. Configured Bosch Receivers are displayed as hardware objects in the victor Device List.

Configuring Alarms and Alarm Categories

Alarms and Alarm Categories must be configured in the Bosch Receiver editor prior to the addition and modifying of Bosch Receivers.

Procedure 4-1-1 Accessing the Alarm Categories Editor

The Alarm Categories Editor is used to add and remove alarm categories.

Step	Action
1	Click on the Device list .
2	Open the Alarm Categories Editor.
3	Click on Alarm Categories.
4	Right-click on the Alarm Categories sub-folder and select Edit. The Alarm Categories box opens with Zone and Partition listed as the default categories.
	- End -

Procedure 4-1-2 Adding Alarm Categories

Step	Action
1	Click Add to add a row for the new Alarm Category.
2	Open the Alarm Categories Editor.
3	Click on the row under the Category Name column.
4	Enter a name for the new Alarm Category (up to 100 characters).
5	Click Save and Close.

Procedure 4-1-3 Removing Alarm Categories

- 1 Open the Alarm Categories Editor.
- **2** Click in the row that contains the Alarm Category that you want to remove.
- 3 Click Remove.
- 4 Click Save and Close.

- End -

Procedure 4-1-4 Accessing the Alarm Configurations Editor

The Alarm Configurations Editor is used to modify existing alarms and add new alarms.

Step	Action
1	Click on the Device list.
2	Click on Alarm Configurations.
3	Right-click on the Alarm Configurations sub-folder and select Edit.
	- End -
Proc	edure 4-1-5 Modifying Existing Alarms
Step	Action
1	Click on the row with the alarm that you want to edit,
2	Make the configuration changes.
	Click Save and Close.
3	Click Save and Close.
3	- End -
	- End -
Proce	- End - edure 4-1-6 Configuring New Alarms
Proce	- End - edure 4-1-6 Configuring New Alarms Action
Proce Step	- End - edure 4-1-6 Configuring New Alarms Action Click Add to add a new row for the new alarm configuration
Processing 1	- End - edure 4-1-6 Configuring New Alarms Action Click Add to add a new row for the new alarm configuration Select the protocol from the Format drop-down list.
Processing 1	- End - edure 4-1-6 Configuring New Alarms Action Click Add to add a new row for the new alarm configuration Select the protocol from the Format drop-down list. Select the category from the Category drop-down list.
Processing 1	- End - edure 4-1-6 Configuring New Alarms Action Click Add to add a new row for the new alarm configuration Select the protocol from the Format drop-down list. Select the category from the Category drop-down list. Note
Processes 1 2 3	- End - edure 4-1-6 Configuring New Alarms Action Click Add to add a new row for the new alarm configuration Select the protocol from the Format drop-down list. Select the category from the Category drop-down list. Note Categories in the list are derived from the Alarm Category configuration
Proce Step 1 2 3	- End - edure 4-1-6 Configuring New Alarms Action Click Add to add a new row for the new alarm configuration Select the protocol from the Format drop-down list. Select the category from the Category drop-down list. Note Categories in the list are derived from the Alarm Category configuration Enter a name for the alarm in the Alarm Name field.
Processes 1 2 3 4 5	- End - edure 4-1-6 Configuring New Alarms Action Click Add to add a new row for the new alarm configuration Select the protocol from the Format drop-down list. Select the category from the Category drop-down list. Note Categories in the list are derived from the Alarm Category configuration Enter a name for the alarm in the Alarm Name field. Enter a code to activate the alarm in the Activation Code field.

- End -



Procedure 4-1-7 Deleting Alarm Configurations

Step	Action
1	Click in the row that contains the Alarm Configuration that you want to remove.
2	Click Remove.
3	Click Save and Close.

Configuring Bosch Receivers

Procedure 4-2-1 Adding a New Bosch Receiver

Step	Action	
1	Click on Create New Item ticon.	
2	Click on the Bosch Receiver icon.	
3	Enter a name for the receiver in the Name text box	
4	Enter a description for the map in the Description text box	
	Note	
	The Enabled check-box is selected by default. To deactivate the receiver, deselect the check-box.	
5	Enter the IP Address of the receiver in the IP Address text box	
6	Double click Alarm Port text-box and edit alarm port value. The default alarm port is 1025	
7	Select next to the Time Zone text-box, the Object Selector dialog box displays.	
8	Select a Time Zone from the right column	
9	Select OK to confirm selection or Cancel to exit	
10	Select Object Selector in the Time Zone text box to edit message filtering options.	
11	In the Message Delivery tab, select Journal Options, then Message Filter Options . See <i>Table 1 on page 14</i> for further information on dialog box selections for Message Filt Options .	
12	Select next to Online, the Object Selector dialog box displays	
13	Select Action Item from the left column. This will filter results in the right column	
14	Select the required event action from the right column	
15	Select OK to confirm selection or Cancel to exit	
16	Select next to Off-line , the Object Selector dialog box displays	
17	Select Action Item from the left column. This will filter results in the right column	
18	Select the required event action from the right column	

19 Select **OK** to confirm selection or **Cancel** to exit

Note

Select next to an **Online** or **Off-line** alert to remove it

- 20 Select in the Associations section. The Object Selector dialog box displays
- 21 Select an association type from the left column. This will filter results in the right column
- 22 Select the required association from the right column. Select **OK** to confirm the selection or **Cancel** to exit
- 23 Repeat steps 19-21 to add more associations

Note

Select an association, then select 👩 to remove it

24 Select Save

Action	Selection in Dialog Box
Journal all activities	Journal to Database
	Activity Viewer
	Report all messages
arm Point Messages are only sent to	Journal to Database
the database	Report all messages for alarm points
arm Point Messages are only sent to	Activity Viewer
the Activity Viewer	Report all messages for alarm points
All configured and non-configured alarms are journaled to the database and the Activity Viewer	Report all messages
No journaling, other than online/offline messages and receiver specific messages.	None

Table 1: Dialog Box Selections for Message Filtering

- End -

Procedure 4-2-2 View All Bosch Receivers

From the Setup tab, users can view all configured Bosch Receivers

Step Action

- 1 Click on Show All Items icon.
- 2 Select the Bosch Receiver icon.



3 All configured Bosch Receivers are displayed in an Object List.

- End -

Configuring Bosch Alarm Points

Procedure 4-3-1 Add New Alarm Point

Alarm points can be configured and defined directly from the device list using the Alarm Point editor.

Step	Action	
1	Expand Bosch Receiver in the Device List by selecting	
2	Right click on the relevant Bosch Receiver	
3	Select New Alarm Point. Alarm Point editor opens	
4	Enter a Name for the Alarm Point	
5	Enter a Description for the Alarm Point	
6	Select the Enabled check-box to enable or de-select to disable. The default setting is enabled	
7	Enter the Panel Account number	
8	Enter the Alarm Port number	
9	Select CID (Contact Identification) or SIA (Security Industry Association) from the Format drop down menu	
10	Select the category from the drop down list	
11	Select Alarm Type from the drop down menu. Available selections are dependant on Format selection	
12	If required, select next to Active alerts, the Object Selector dialog box displays	
13	Select Action Item from the left column. This will filter results in the right column	
14	Select the required object from the right column	
15	Select OK to confirm selection or Cancel to exit	
16	If required, select next to Inactive alerts, the Object Selector dialog box displays	
17	Select Action Item from the left column. This will filter results in the right column	
18	Select the required object from the right column	
19	Select OK to confirm selection or Cancel to exit	
20	Select 🕞 in the Associations section. The Object Selector dialog box displays	
21	Select an association type from the left column. This will filter results in the right column	
22	Select the required association from the right column. Select \mathbf{OK} to confirm the selection or \mathbf{Cancel} to exit	

23 Repeat steps 19-21 to add more associations

Note

Select an association, then select 🐼 to remove it

24 Select Save

Note

If victor Unified Client is out of sync with the Bosch Receiver, then status messages from the panel are not communicated. To overcome this, an option is provided for Alarm Point to activate and deactivate from the **Device List** and **Dynamic View**. This changes the status in victor Unified Client that will not be downloaded to the receiver.

- End -

Procedure 4-3-2 Importing Alarm Points

Step Action

1 Create a .txt or .csv file containing the required alarm point data, as shown in Figure 4-1 Import Alarm Points Data.

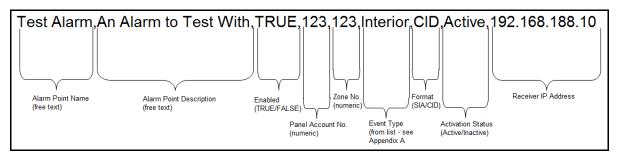


Figure 4-1 Import Alarm Points Data

- 2 Save the .txt or .csv file.
- 3 Click on Create New Item icon.
- 4 Click on the Import Alarm Point icon. Please select a file to import dialog box displays.
- 5 Navigate to the location of the saved .txt or .csv file.
- 6 Select Open.
- 7 Reading alarm points file dialog opens, displaying whether import has been successful or not.
- 8 Select Close.

- End -



Procedure 4-3-3 Editing Alarm Points

Alarm Point editor allows changes to Alarm Points already configured.

Step	Action	
1	Click on Edit Existing Item icon.	
2	Select the Bosch Alarm Point icon.	
3	Select the Created Alarm Point to be edited. Make edits as required.	
4		
5	Select Save.	
	- End -	

Step	Action	
1	Click on Show All Items icon.	
2	Select the Alarm Point icon.	
3	All configured alarm points are displayed in an Object List.	
	- End -	

Troubleshooting

Troubleshooting

This section provides troubleshooting information for issues that may occur in the Bosch Integration.

Problem:

Sometimes the installation may fail if the CrossFire service does not stop on time and throws a time out error.

Solution:

Ensure that you have completed the following steps:

- Check if the CrossFire service is stopped from services panel in case of installation failure. Refer to Figure 5-1 CrossFire Services on page 18.
- Wait till the CrossFire service is stopped and then trigger the installation again. This will work fine as the service is stopped already.

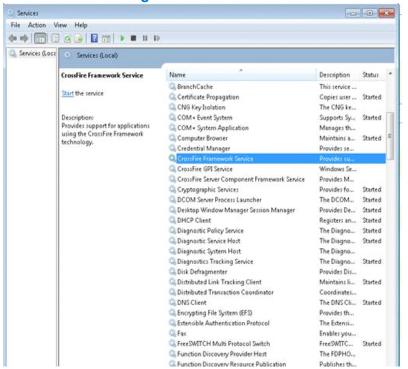


Figure 5-1 CrossFire Services



Appendix A

Journal Log Messages

Bosch Messages logged in the victor Activity Viewer

Message Type	Message Description
Device Activity	Device online status messages (unknown, online, offline)
Device Activity	SIA messages
Device Activity	CID messages
System Activity	Start up driver messages
System Activity	Stop driver messages
Device Activity	Modem IIIa2 messages (Bosch only)
Device Activity	Modem IV messages (Bosch only)

Note

Alarms are received and saved in the Journal database even though the Alarm point is not configured. You can search the alarm against the configured Bosch receiver as a primary object.

Journaling

If the alarm point is configured, journalling will be contain the following messages.

Activation Messages

- · Alarm Point "Alarm Point Name" activation occurred on Receiver "Receiver Name"
- Alarm Point "Alarm Point Name" activation occurred by User "User Code" on Receiver "Receiver Name"

Deactivation Messages

- Alarm Point "Alarm Point Name" deactivation occurred on Receiver "Receiver Name".
- Alarm Point "Alarm Point Name" deactivation occurred by User "User Code" on Receiver "Receiver Name",

If the alarm point is not configured, journaling will be carried out in the following way:

 If an alarm is not configured as alarm configuration, the alarm code will be journaled instead of the alarm name.



- 'Alarm Code' is activated on panel account number #1234 at Receiver 'Receiver Name'
- 'Alarm Code' is restored on panel account number #1234 at Receiver 'Receiver Name'
- If an alarm is configured as alarm configuration, the name of the alarm code will be journaled.
 - "Alarm Name" is activated on panel account number #1234 at Receiver 'Receiver Name'
 - 'Alarm Name' is restored on panel account number #1234 at Receiver 'Receiver Name'